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Furuta et al.

(54) PASSENGER CARRYING MOBILE ROBOT

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See application file for complete search history.

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(57) ABSTRACT

A single passenger carrying mobile robot, includes a single operated member that is operated by a passenger to instruct both a moving direction and a moving speed of the passenger carrying mobile robot, a moving member configured to move the passenger carrying mobile robot and a controller configured to control the moving member based on input information input to the operated member by the passenger, wherein the passenger carrying mobile robot further includes a sensor that acquires obstacle information of a surrounding of the passenger carrying mobile robot, and the controller predicts an expected course of the passenger carrying mobile robot based on the input information and determines based on the obstacle information whether or not an obstacle is located in the expected course, and changes a control of the moving member when determining that the obstacle is located.

16 Claims, 14 Drawing Sheets

